

MGF \bar{P}_s approach. Combined average error and outage Impact of delay spread and Doppler, Intro to diversity

Lecture Outline

- **Moment Generating Function Approach to compute \bar{P}_s** (*not covered in lecture*)
- **Combined Outage and Average Probability of Error**
- **Delay Spread Effects on Error Probability**
- **Doppler Effects on Error Probability** (*not covered in lecture*)
- **Introduction to Diversity**

1. Moment Generating Function technique (*not covered in lecture*)

- The alternate Q function representation is

$$Q(z) = \frac{1}{\pi} \int_0^{\pi/2} \exp\left[\frac{-z^2}{2 \sin^2 \phi}\right] d\phi.$$

- Using this alternate Q function representation, the average error probability is given by

$$\bar{P}_s = \alpha \int_0^\infty Q(\sqrt{2g\gamma_s}) p(\gamma_s) d\gamma_s = \alpha \int_0^\infty \frac{1}{\pi} \int_0^{\pi/2} \exp\left[\frac{-2g\gamma_s}{2 \sin^2 \phi}\right] d\phi p(\gamma_s) d\gamma_s.$$

- Since the inner integral is bounded, we can switch the order of integration, yielding

$$\bar{P}_s = \frac{\alpha}{\pi} \int_0^{\pi/2} \mathcal{M}\left(\frac{-g}{\sin^2 \phi}; \bar{\gamma}_s\right) d\phi,$$

where

$$\mathcal{M}(s; \bar{\gamma}_s) = \int_0^\infty e^{s\gamma_s} p(\gamma_s) d\gamma_s$$

is a moment generating function (MGF) of the distribution $p(\gamma_s)$ and is in the form of a Laplace transform.

- The MGF for any distribution of interest can be computed in closed-form using classical Laplace transforms.
- If Laplace transform is not in closed form, it is easily computed numerically for most fading distributions of interest.
- The parameter $s = -g/\sin^2 \phi$ of the moment generating function depends on the modulation via g .

2. MGF for common fading distributions (*not covered in lecture*)

- The MGF corresponding to the most common distributions are given as

$$\text{Rayleigh : } \mathcal{M}_r\left(-\frac{g}{\sin^2 \phi}; \bar{\gamma}_s\right) = \left(1 + \frac{g \bar{\gamma}_s}{\sin^2 \phi}\right)^{-1}.$$

Ricean with factor k : $\mathcal{M}_k \left(-\frac{g}{\sin^2 \phi}; \bar{\gamma}_s \right) = \frac{(1+k) \sin^2 \phi}{(1+k) \sin^2 \phi + g \bar{\gamma}_s} \exp \left(-\frac{k g \bar{\gamma}_s}{(1+k) \sin^2 \phi + g \bar{\gamma}_s} \right)$.

Nakagami- m : $\mathcal{M}_m \left(-\frac{g}{\sin^2 \phi}; \bar{\gamma}_s \right) = \left(1 + \frac{g \bar{\gamma}_s}{m \sin^2 \phi} \right)^{-m}$.

- All of these functions are simple trigonometrics and are therefore easy to integrate over a finite range.

3. Average Probability of Error with MGF (not covered in lecture)

- To compute the average probability of error for BPSK modulation in Nakagami fading, we use the fact that for an AWGN channel BPSK has $P_b = Q(\sqrt{2\gamma_b})$, so $\alpha = 1$ and $g = 1$ in average error probability expression above.
- Using the moment generating function for Nakagami- m fading and substituting this into the average error probability integral with $\alpha = g = 1$ yields

$$\bar{P}_b = \frac{1}{\pi} \int_0^{\pi/2} \left(1 + \frac{\bar{\gamma}_b}{m \sin^2 \phi} \right)^{-m} d\phi.$$

4. Combined outage and average error probability:

- Shadowing causes outage and flat-fading determines \bar{P}_s during nonoutage
- \bar{P}_s obtained in small region where $\bar{\gamma}_s$ approximately constant as $\bar{P}_s = \int P_s(\gamma_s) p(\gamma_s | \bar{\gamma}_s)$.
- A target $\bar{\gamma}_s$ is needed to obtain a target \bar{P}_s .
- Outage occurs when shadowing causes $\bar{\gamma}_s$ to fall below its target value.

5. Delay Spread (ISI) Effects on Performance.

- Delay spread exceeding a symbol time causes ISI (self-interference).
- ISI leads to an irreducible error floor. Approximated as $\bar{P}_{b, floor} \approx (\sigma_{T_m} / T_s)^2$.
- Without ISI compensation, avoid error floor by reducing data rate: $T_s \gg T_m$ or $R \leq \log_2(M) \times \sqrt{\bar{P}_{b, floor} / \sigma_{T_m}^2}$.

6. Doppler Spread Effects on Performance (not covered in lecture)

- Doppler causes the channel phase to decorrelate.
- Doppler impacts coherent modulation if an accurate coherent phase reference cannot be obtained at the receiver. A noisy phase estimate leads to large errors.
- Phase decorrelation between symbols leads to an irreducible error floor for differential modulation.
- Error floor approximated by $P_{b, floor} \approx .5(\pi B_d T_b)^2$.

7. Introduction to Diversity

- Basic concept is to send same information over independent fading paths.
- Paths are combined to mitigate the effects of fading.

8. Realization of Independent Fading Paths

- Space Diversity: Multiple antenna elements spaced apart by decorrelation distance.
- Polarization Diversity: Two antennas, one horizontally polarized and one vertically polarized.
- Frequency diversity: Multiple narrowband channels separated by channel coherence bandwidth.
- Time diversity: Multiple timeslots separated by channel coherence time.

9. Array and Diversity Gain

- Array gain is the gain in SNR from noise averaging over the multiple antennas. Gain in both AWGN and fading channels.
- Diversity gain is the change in slope of the probability of error due to diversity. Only applies to fading channels.

Main Points

- Easy to compute average P_s using alternate Q function and MGF approach: becomes a simple finite range integral of the MGF for the fading distribution.
- In combined fast and slow fading, outage is determined by shadowing, and average probability of error computed by averaging over the fading distribution conditioned on a fixed path loss and shadowing.
- Fading greatly degrades performance.
- Need to find ways to combat flat fading (adaptive modulation, which adapts to fading, or diversity, which removes fading).
- ISI leads to an irreducible error floor at high data rates - much work on ISI mitigation in current systems.
- Diversity is a powerful technique to overcome the effects of flat fading by combining multiple independent fading paths
- Diversity typically entails some penalty in terms of rate, bandwidth, complexity, or size.